

ORBIT

ENGINEERING EXPO

ROBO WAR

Rule book v2

Weight Category - 15 Kg

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ENGINEERS VLOGS

1. TASK

Design and construct a remote-controlled robot capable of fighting a tournament against another robot(s).

2. DESIGN SPECIFICATIONS

A. Specifications:

1. There will be no restrictions on the dimensions of the bot(s).
2. The weight of the machine should not exceed 15 Kgs (33.07 Lbs.), which includes the weight of any pneumatic source/tank. All pneumatic tanks/source and batteries should be on board. Only the weight of the remote controller will not be counted.
3. A bot can be in a "Cluster Bot" formation. Each bot must meet the requirements described in this problem statement. The total weight of all the bots and the dimensions of the combination of bots must satisfy the above two points.
4. Robots with pneumatic or hydraulic mechanisms or electric lifters are allowed.

B. Mobility:

All robots must have easily visible and controlled mobility in order to compete.

Methods of mobility include:

1. Rolling (wheels, tracks or the whole robot).
2. Non-wheeled: non-wheeled robots have no rolling elements in contact with the floor and no continuous rolling or cam operated motion in contact with the floor, either directly or via a linkage, but are not true walkers as defined below. Motion is "continuous" if continuous operation of the drive motor(s) produces continuous motion of the robot. Linear-actuated legs and novel non-wheeled drive systems are also allowed under this category.
3. Manually operated jumping and hopping are allowed. However, the maximum height of any part of the machine should not exceed 6ft during any stage of its jumping/hopping and any damage caused due to this mechanism is solely the responsibility of the team.

Mobility methods that are NOT allowed:

1. Flying (using airfoil, helium balloons, ornithopters, etc.) is not allowed.
2. The robots should not secure itself on the ring surface by using suction cups, diaphragms, sticky treads, glue or other such devices.

C. Robot Control Requirements:

1. The robot must be controlled only through a wireless remote, while all power supply must be on board.
2. Control must be exhibited over all of its functions and positions. Although autonomous functions within the bot are acceptable, the controller must be able to remotely disable or override these functions at any time. Note that any damage due to this function is the responsibility of the team, and there must compulsorily be a manual emergency stop (E-

stop) function that can be controlled from the radio controller to manually override this autonomous function in case of emergency.

3. There should be binding capability between transmitters and receivers and they must be able to connect between polycarbonate (20mm), metal bars and barriers. Only remotes with such a facility will be allowed.
4. The team must have an at least four-frequency wireless remote-control circuit or two dual control circuits which may be interchanged before the start of the race to avoid frequency interference with other teams. Cases of any interference in the wireless systems will not be considered for rematch or results.
5. Remote control systems from toys may be used. Remote control systems available in the market may also be used, while nonstandard or self-made remote-control systems can be used only after approval from the organizers.
6. The team should pair up the wireless remote with the machine before putting it into the arena. No extra time will be provided for this once the machines are put inside the arena, and not connecting the remote with the machine prior to that may attract a penalty on the team.

D. Battery and Power:

1. The machine must be powered electrically. Use of an IC engine in any form is not allowed. Onboard batteries must be sealed, immobilized-electrolyte types (such as gel cells, lithium, NiCad, NiMH, or dry cells).
2. The electric voltage between any 2 points on the machine should not exceed 24V DC at any point in time. Participants will have to bring their own converters for standard power supply.
3. Participants must protect the battery terminals from a direct short and causing a battery fire, failure to do so will cause direct disqualification.
4. Use of damaged, non-leak proof batteries may lead to disqualification.
5. Special care should be taken to protect the onboard batteries. If the judges find that the battery is insufficiently protected, the team will be disqualified immediately.
6. Change of battery will not be allowed during the match.
7. Only bots with onboard batteries will be allowed.
8. The supply from the battery to all the weapons and power systems should qualify the following fail-safes:
 - a. A manual disconnect (switch) that can be turned off without harming the person doing it, i.e. No body parts or weapons should come in the way of the switch.
 - b. Manual emergency stop that can be triggered through the radio controller.

The teams are suggested to have at least one extra battery ready and charged up during competition so that on advancing to the next level, they won't have to wait or suffer due to the uncharged battery (Refer section "Match Frequency"). **If teams do not show up during their allotted slot, they will be disqualified.**

E. Pneumatics

9. A robot can use pressurized non-flammable gasses to actuate pneumatic devices. Maximum allowed outlet nozzle pressure is **50 bars***. The storage tank and pressure regulators used by teams need to be certified and teams using pneumatics are required to produce the Safety and Security letters at the Registration Desk at the venue. **Failure to do so will lead to direct disqualification.** Also note that we will not be providing any mechanism to refill the pneumatic cylinders/containers of maximum pressure exceeding the limit mentioned above.
10. Participants must be able to indicate the used pressure with an integrated or temporarily fitted pressure gauge. Also, there must be some provision to check the cylinder pressure on the bot.
11. The maximum pressure in a cylinder must not exceed the rated pressure at any point of time. All pneumatic components must be rated to at least the value of maximum pressure.
12. The participants must have a safe way of refilling the system and determining the on-board pressure.
13. All pneumatic components on board a robot must be securely mounted. Care must be taken while mounting the pressure vessel and armor to ensure that, if ruptured, nothing escapes the robot. The terms 'pressure vessel, bottle, and source tank' are used interchangeably. The entire pneumatic setup should be on board. No external input (from outside the arena) can be given to the robot for functioning of its pneumatic system.

E. Hydraulics:

1. A robot can use non-inflammable liquid to actuate hydraulic devices, like cylinders.
2. All hydraulic components on-board must be securely mounted. Special care must be taken while mounting the pump, accumulator and armor to ensure that if ruptured direct fluid streams will not escape the robot.
3. All hydraulic liquids are required to be non-corrosive and your device should be leak proof.
4. Maximum allowed pressure is 50 bars*.
5. Participants must be able to indicate the used pressure with integrated or temporarily fitted pressure gauge.
6. The entire hydraulic setup should be on board, no external input (from outside the arena) can be given to the robot for functioning of its hydraulic system.

F. Weapon Systems:

1. Robots can have any kind of magnetic weapons, cutters, flippers, saws, lifting devices, spinning hammers etc. (if they qualify the criteria mentioned below) as weapons.
2. Following weapons cannot be used:
 - a. Liquid projectiles (Foam, liquefied gasses)
 - b. Any kinds of inflammable liquids
 - c. Weapons causing invisible damage (Electrical weapons, RF jamming weapons and others).

- d. Weapons causing opponents' weapons (spinners) to entangle in them (Chains, Ropes or loose Fabrics).
 3. Spinning weapons:
 - a. The weapon must come to a full stop within 60 seconds of the power being removed using a self-contained braking system.
 4. Spring-loaded or flywheels:
 - a. Under no circumstances must a large spring be loaded when the robot is out of the arena or testing area.
 - b. All springs, flywheels, and similar kinetic energy storing devices must fail to a safe position on loss of radio contact or power.
 5. Flame based:
 - a. Flame rules may change subject to infrastructural and safety limitations.
 - b. Fuel must exit the robot and be ignited as a gas. It cannot leave the robot in a liquid or gelled form or use oxidizers.
 - c. Fuel types allowed are propane and butane, the maximum quantity allowed is 470ml.
 - d. The ignition system must have a remotely operated shut-off that allows the controller to disable it using the radio control system.

3. COMPETITION RULES AND SPECIFICATIONS

A. Team Specifications:

1. A team may consist of a maximum of 4 participants. These participants can be from the same or different institutes.
2. Team Name: Every team must have a unique name. Organizers reserve the right to reject entries from any team whose name it deems inappropriate, offensive or conflicting. Organizers must be notified if a team's name has been changed.
3. Team Representative: Each team must specify their team representative (leader) at the time of registration on the website. All the important communications between Organizers and the registered teams will be done through their team representative. The team representative must submit valid contact details (phone no., email ID etc.) at the time of registration.

B. Registration:

Start preparing your bots for the competition. A mail will be sent when the registration portal goes live.

Teams using pneumatics or hydraulics will have to send a safety letter containing targeted maximum pressure and type of equipment to be used, signed by any faculty in-charge/lab in-charge or a testing lab/company dealing in this field, on their official letterhead.

C. Submission of Abstract:

Participants have to submit a portfolio of their machine, consisting of a written abstract and a video of the working model before the competition. This portfolio will be used to seed teams for the competition.

D. Details regarding the abstract:

(This section pertains to the general abstract to be submitted by every team)

Written Abstract:

1. The weapon systems and power supply method must be explained in detail, along with proper diagrams and pictures.
2. The functioning of wireless remote or any other wireless module used for wireless remote, and its frequency, must be explained in detail.
3. A description of any unusual advantageous mechanism used must be given. The specifications of all the components used, including motors, suspension springs, remote controller, wires, battery etc. have to be mentioned.
4. You can email the portfolio minus the video and send the video later, thus making sure that at least the abstract of your portfolio reaches us before the deadline. An email will be sent to the team leader confirming the receipt of the entry. Each team must make an online submission only by email. In the case of multiple submissions, only the first submission will be used for judging purposes.
5. All submissions must be made online before the deadline.
6. Soft copy of the permission regarding pneumatics and hydraulics capacity must be mailed to us before the deadline. A hard copy of the permission must be brought with you to the competition. Teams failing to do any of this (soft copy submission and hard copy presence), will not be allowed to participate.

Video Abstract:

1. The video should be of at least 1 minute with the unedited clip showing the machine performance to the fullest. All destructive mechanism(s) being used must be shown with their workings. We may demand another clip at a later stage from the participants who qualify Round one. Instructions for the same will be sent by mail to such participants.
2. Participants are not required to explain the mechanisms in the video. All portfolios will be used strictly for seeding purposes. The elimination procedure will be objective and the evaluation of every participant will be published on the website. Orbit assures total privacy of the material submitted to us. The portfolio of your machine will be helpful in the future as evidence of your hard work along with determining your position for the competition. Hence, please pay adequate attention to it.

All submissions must be made online before the deadline.

NOTE: Judges will go very thoroughly over the video and written abstracts and then shortlist the robots which would be allowed to perform in the competition. The portfolio is meant to assess the efforts put in by the participants. Thus, even if you are not able to meet the requirements asked in the portfolio, please send us the portfolios based on the current state of your machine

before the deadline. That is, even if your machine is incomplete, please send the portfolios anyway, instead of not sending them or sending them late.

E. Match Duration and Type:

Matches will consist of 3 minutes of active fight time exclusive of any time-outs.

Hence, it is not binding but advisable to keep battery capacity, power usage and machine defenses such that they can sustain a 3- minute fight.

The matches can be of the following types:

1. Match: A regular 1-on-1 combat between 2 robots

2. Rumble: A combat between more than 2 robots simultaneously

A detailed document of rules regarding the format and rules to be followed during the event days shall be uploaded later, and the participants will be informed.

F. Match Frequency:

A team is allowed to prepare for the next match for a period of 30 minutes. This time is calculated from the time the robot leaves the post-match staging area of its previous match. If the team fails to return with the robot ready to the pre-match staging area when called after the allotted time, the team may be forced to forfeit.

It is recommended that any routine maintenance (i.e. battery charging) should be capable of being performed well within this time period, or backup should be kept.

In extreme cases, the 30-minute time period may be lengthened at the discretion of the event organizers.

G. Criteria for victory:

1. A robot is declared victorious if its opponent is immobilized.
2. A robot will be declared immobile if it cannot display the linear motion of at least one inch in a time period of 10 seconds. A bot with one side of its drivetrain disabled will not be counted out if it can demonstrate some degree of controlled movement. In case both the robots remain mobile after the end of the round, the winner will be decided subjectively.
3. A robot that is deemed unsafe by the judges after the match has begun will be disqualified and therefore declared the loser. The match will be immediately halted and the opponent will be awarded a win.
4. If a robot is thrown out of the arena the match will be stopped immediately, and the robot inside the arena will automatically be declared as the winner.
5. Robots cannot win by pinning or lifting their opponents. Organizers will allow pinning or lifting for a maximum of 20 seconds per pin/lift then the attacker robot will be instructed to release the opponent. If, after being instructed to do so, the attacker is able to release but does not, their robot may be disqualified. If two or more robots become entangled or a crushing or gripping weapon is employed and becomes trapped within another robot, then the competitors should make the timekeeper aware, the fight should be stopped and the robots separated by the safest means.

6. If a bot gets stuck inside the arena due to the deformity of the arena itself. The timer will be stopped and the bot will be released by the safest means.
7. Points will be given on the basis of **aggression, damage and control**.

a. **Aggression:** Aggression is judged by the frequency, severity, boldness and effectiveness of attacks deliberately initiated by the robot against its opponent.

If a robot appears to have accidentally attacked an opponent, that act will not be considered when judging for aggression.

b. **Control:** Control is judged in terms of the ability to attack an opponent at its weakest point, using weapons in the most effective way, and minimizing the damage caused by the opponent.

c. **Damage:** Through deliberate action, a robot either directly or indirectly reduces the functionality, effectiveness or defensibility of an opponent. Damage is not considered relevant if a robot inadvertently harms itself. Also, if a pressure vessel or a rapidly spinning device on a robot fragments, any damage to the opponent will not be considered "deliberate".

NOTE: A robot winning in a round against its opponent doesn't guarantee its entrance into the next round. If the judges found the winner robot incompetent to enter into the next round, it may get disqualified. Judges can disqualify both the robots of a match from advancing to the next round. All the decisions taken by the judge will be final and binding to all. Any queries afterwards will not be entertained.

H. Event Specific Terminology:

1. Disabled: A robot is not functioning correctly due to either an internal malfunction or contact with the opposing robot or Arena Hazard.
2. Disqualification: A robot is no longer permitted to compete in the current Robowars tournament.
3. Immobilized: In the judges' opinion, a robot is not responsive for a specified period of time.
4. Knockout: Occurs when the attack or deliberate actions of one robot causes its opponent to become immobilized.
5. Lifting: Occurs when one robot controls an opponent's translational motion by lifting the drive mechanism of the opponent off of the Arena floor.
6. No Contact: Neither robot makes contact with the other for a specified period of time.
7. Pinning: Occurs when one robot, through sheer force, holds an opponent stationary in order to immobilize it.
8. Radio Interference: Refers to a situation where at least one robot becomes unresponsive or non-controllable due to the effect of the other robot's remote-control signal.
9. Non-Responsive: In the judges' opinion, the robot cannot display some kind of controlled translational movement along the arena floor.
10. Restart: Occurs after a fault or a timeout has been declared and the competing robots are ready to continue.

11. Stuck: A robot is hung-up in a part of the arena, an arena hazard or an opponent, such that it is effectively non-responsive.
12. Tap-Out: Occurs when a robot's operators decide that they no longer want to continue the match and concede the win to the opposing team.
13. Technical Knockout: Occurs when a robot wins due to immobilization of its opponent even though, in the judges' opinion, no action of the winning robot caused the opponent's immobilization.
14. Timeout: A temporary halting of a match. Timeouts are usually called to separate robots but can be called for other reasons as well.

I. Certificate Policy:

1. Certificate of Excellence will be given to all the winners.
2. Certificates of Participation will be given to all the teams.
3. The teams which get disqualified due to disobeying any of the competition rules will not be considered for the certificate.

J. Safety Rules:

Compliance with all event rules is mandatory. It is expected that competitors stay within the rules and procedures of their own accord and do not require constant policing.

1. Special care should be taken to protect the onboard batteries and pneumatics but without proper protection will not be allowed to compete.
2. If you have a robot or weapon design that does not fit in this ruleset (even having some elements that are not mentioned as allowed/disallowed in this ruleset) or is somehow ambiguous, please contact Engineers Vlog at the earliest. Safe innovation is always encouraged, but surprising the organizers with your brilliant exploitation of a loophole may cause your robot to be disqualified before it even competes.
3. Each event has safety inspections. Your team will be allowed to compete at the sole discretion of Orbit authorities, to whom as a builder you are obligated to disclose all operating principles and potential dangers to the inspection staff.
4. Proper activation and deactivation of robots are critical. Robots must only be activated in the arena, testing areas, or with the expressed consent of the event coordinators.
5. All weapons must have a safety cover on any sharp edges.
6. All participants build and operate robots at their own risk. Combat robotics is inherently dangerous. There is no amount of regulation that can encompass all the dangers involved. Please take care to not hurt yourself or others when building, testing and competing. Any kind of activity (repairing, battery handling etc.) which may cause damage to the surroundings during the stay of the teams in the competition area should not be carried out without the consent of the organizers. Not following this rule may result in disqualification.
7. All the resources provided at the time of competition from the organizers should be strictly used only after the consent of the organizers.
8. Once the robots have entered into the arena, no team member can enter into the arena at any point of time. In case if a fight has to be halted in between and some changes

have to be done in the arena or condition on the robot(s), it will be done by organizers only.

4. ARENA SPECIFICATIONS

Safety Precautions:

The battle area available to the robots for motion during the match is 5in inside the polycarbonate walls, to prevent direct impact. The arena is protected by bulletproof polycarbonate walls of 12mm thickness at four sides (excluding the top).

Arena Diagram:

The out-to-out dimension of the arena will be **14ft x 14ft (l x b)**.

*These figures/parameters are subject to change. The maximum pressure limit may be upgraded depending on the equipment available. The arena size is also subject to the infrastructure. Polycarbonate thickness may be increased. They will be conveyed through updates to this document, as per the “Important Note” below.

5. PRIZES

The prize money will be processed within 25 working days after receiving the prize money from our sponsors.

AN IMPORTANT NOTE:

These rules may change at any time, even without explicit notification to teams.

However, the document uploaded here is to be followed as the latest problem statement for all the rules and design specifications. Any change can be observed in the name of the document which will contain a higher version (v2.0, say) if updated. The teams acknowledge that they have a responsibility to read, understand and abide by the rules and Engineers Vlogs reserves the right to prevent any team from competing at any time for any reason (including but not limited to the reasons specified elsewhere in this document). However, we shall inform all registrants in case an updated version comes up (all the registrant till the date of revision). In case of any queries, participants are encouraged to contact organizing committee of Orbit Engineering Expo, Engineers Vlogs.

ENGINEERS VLOGS